



# REAL-TIME OBJECT DETECTION FOR DISASTER RESPONSE

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# WEBINAR AGENDA

- Motivation: Finding people after a disaster
- Fast Intelligent Video Analytics (IVA) inference using **NVIDIA DeepStream 4.0**
- Introducing **Transfer Learning Toolkit (TLT) for Intelligent Video Analytics**
- Training an object detector using TLT
- Deploying to Jetson AGX Xavier using DeepStream

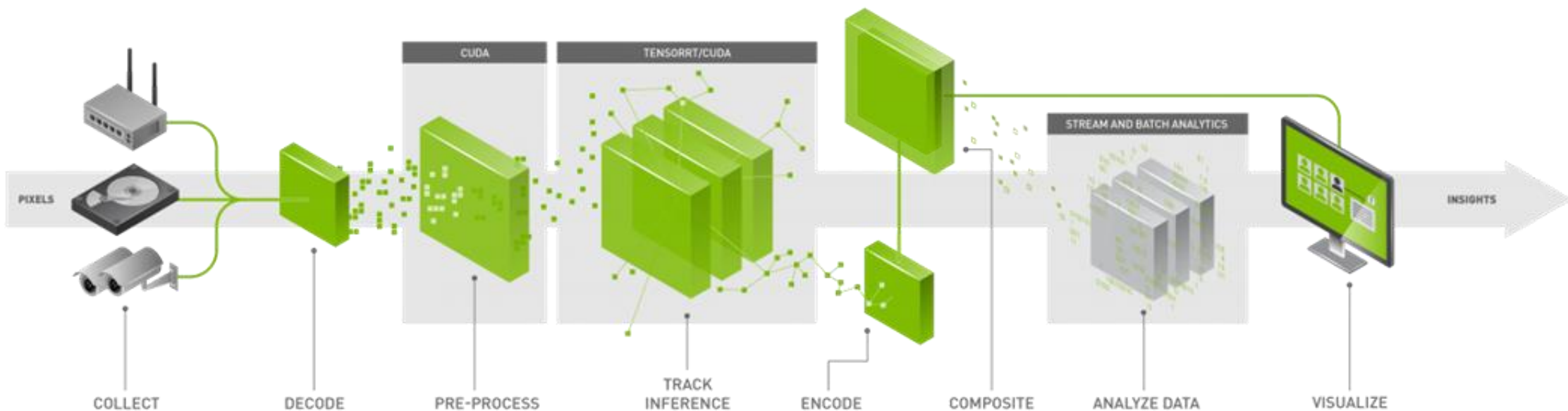




New Orleans (Aug. 30, 2005) U.S. Coast Guard Petty Officer 2nd Class Shawn Beaty looks for survivors in the wake of Hurricane Katrina

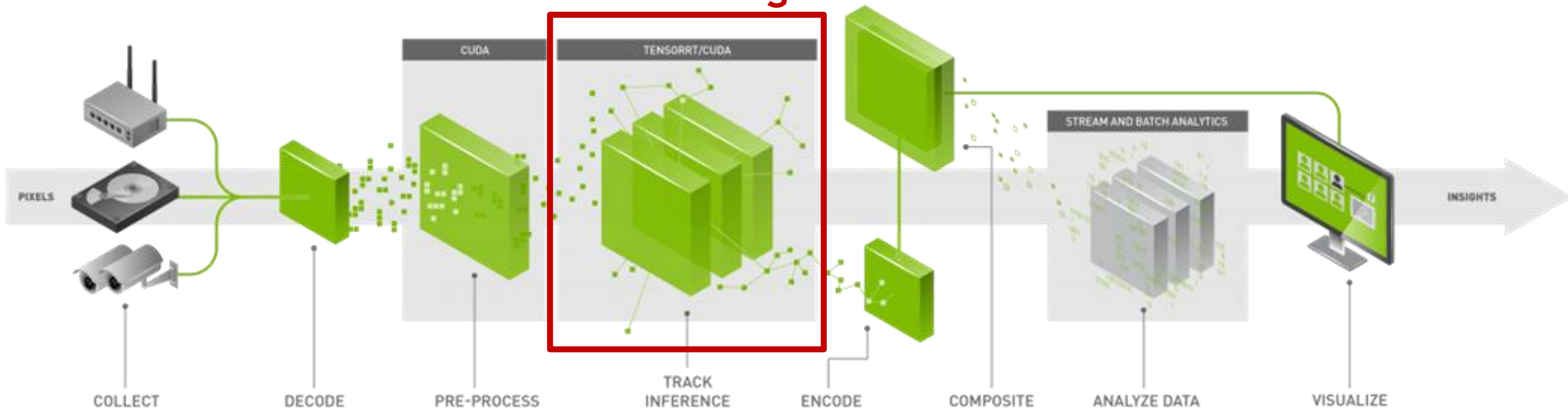
[https://www.navy.mil/view\\_image.asp?id=27531](https://www.navy.mil/view_image.asp?id=27531)

# FAST IVA INFERENCE USING DEEPSTREAM



# FAST IVA INFERENCE USING DEEPSTREAM

We create this model in  
Transfer Learning Toolkit



# NVIDIA TRANSFER LEARNING TOOLKIT FEATURES

## Efficient Pre-Trained Models

GPU-accelerated high performance models trained on large scale datasets.

## Faster Inference with Model Pruning

Model pruning reduces model size, accelerating inference

## Training with Multiple GPUs

Re-training models using multi-GPU training using an easy to use tool

## Abstraction

Abstraction of deep learning, using a simple intuitive interface.

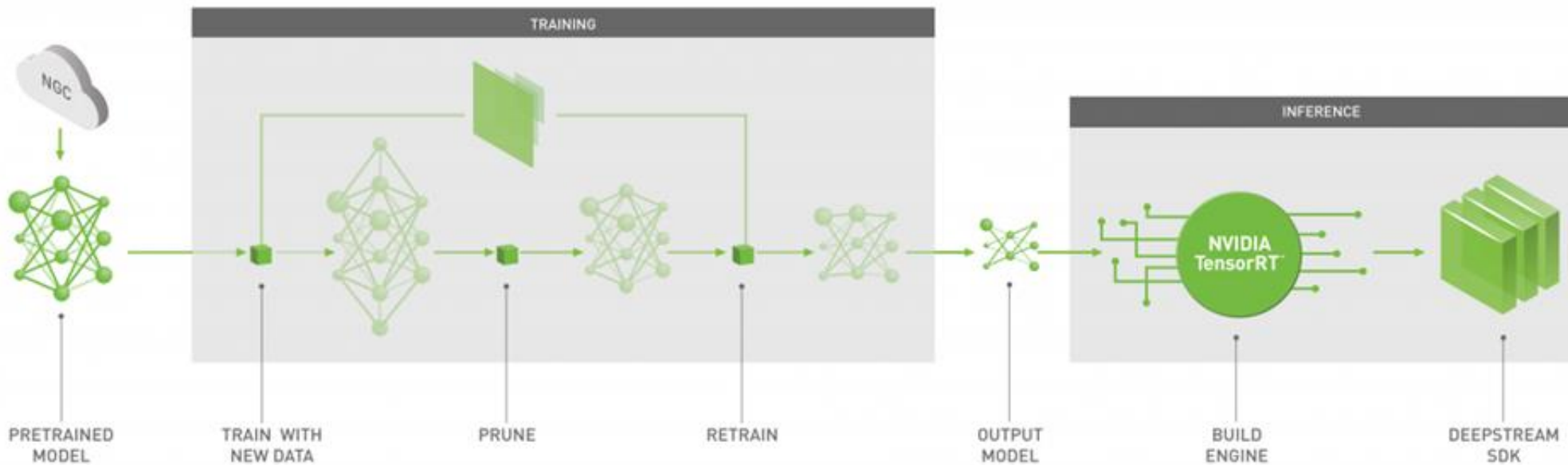
## Containerization

Packaged in a container on the NVIDIA GPU Cloud.

## Integration

Integration with DeepStream SDK simplifies the process of creating IVA applications.

# TRANSFER LEARNING TOOLKIT



On Tesla GPU (eg DGX-1, cloud provider)

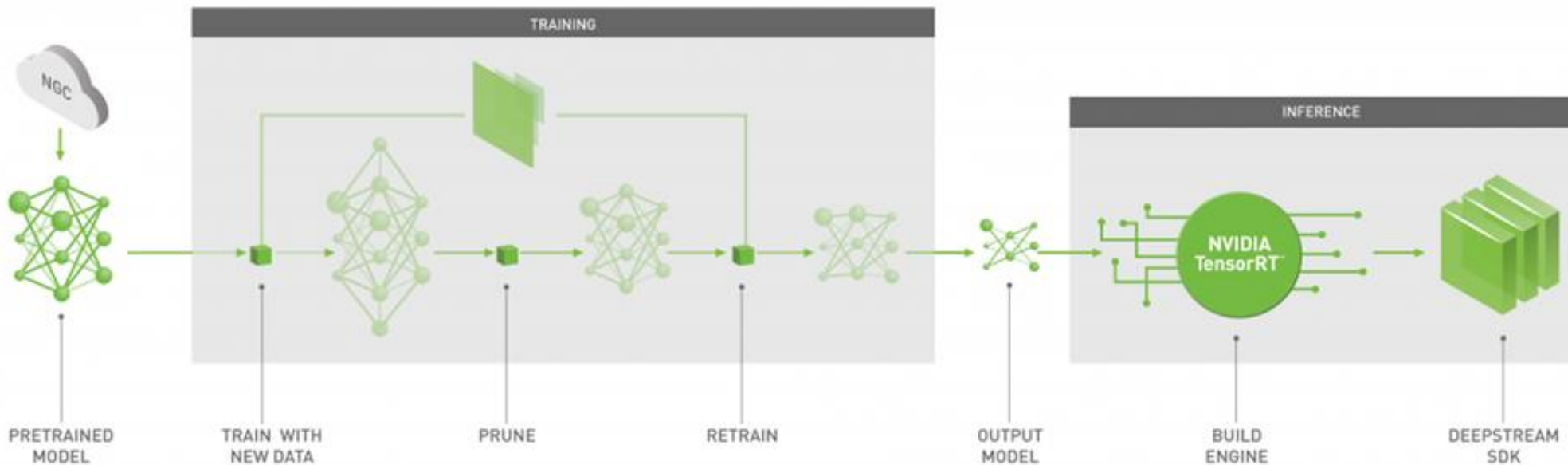
**1. Download pre-trained model**

**2. Convert data to TFRecords**

**3. Train model on your data**



# TRANSFER LEARNING TOOLKIT

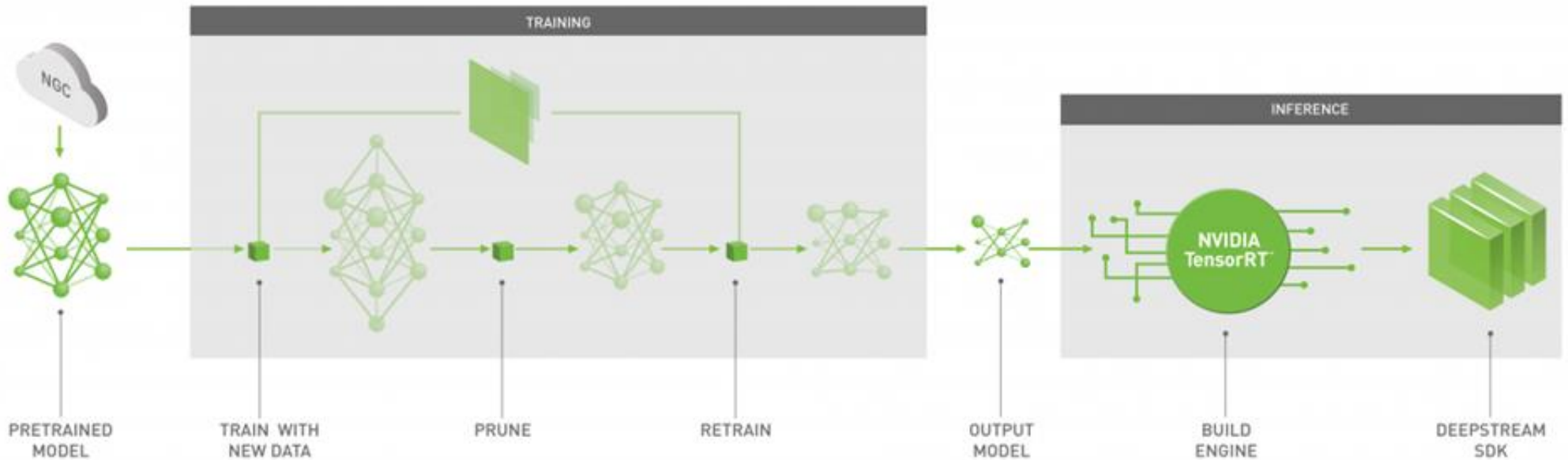


On Tesla GPU (eg DGX-1, cloud provider)

1. Download pre-trained model
2. Convert data to TFRecords
3. Train model on your data
4. (Prune trained model)
5. (Retrain)
6. Export model



# TRANSFER LEARNING TOOLKIT



On Tesla GPU (eg DGX-1, cloud provider)

1. Download pre-trained model
2. Convert data to TFRecords
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4. (Prune trained model)
5. (Retrain)
6. Export model

On edge device (eg Jetson AGX Xavier)

7. (Build TensorRT engine)
8. Deploy in DeepStream

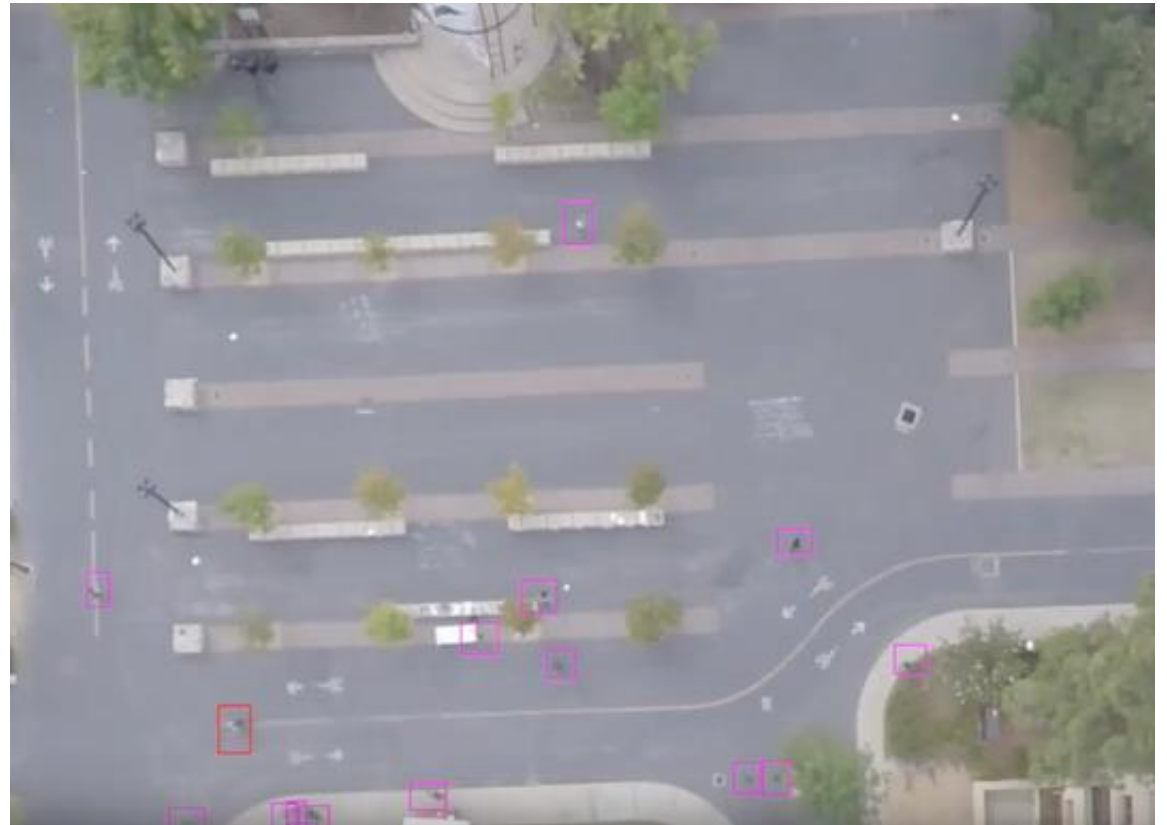


**USING TLT TO TRAIN A  
REAL-TIME DETECTOR**

# STANFORD DRONES DATASET

[http://cvgl.stanford.edu/projects/uav\\_data/](http://cvgl.stanford.edu/projects/uav_data/)

- 68 videos
- Randomly take frames from each video & crop each to 768 x 768.
- Save data in KITTI format.
- Six classes, including pedestrian.
- You could also fine-tune on a domain specific dataset.



# TLT PROCESS IN ONE SLIDE

- `ngc registry model download-version`
- `tlt-dataset-convert`
- `tlt-train`
- `tlt-evaluate / tlt-infer`
- `tlt-prune`
- `tlt-train`
- `tlt-export --data_type fp16`
- **(Jetson) `tlt-converter - fp16`**
- Download a pre-trained model
- Convert KITTI dataset into TFRecords
- Train model using your data
- Evaluate on val data / infer new images
- Prune the model, to reduce no. of params.
- Retrain, to recover accuracy.
- Export your model to .etlt format
- Convert to TensorRT engine.



The background features a complex network of glowing green lines and nodes. The nodes are small, bright green circles of varying sizes, some appearing as larger, softer bokeh-like shapes. The lines are thin, semi-transparent green, crisscrossing the dark space to form a web-like structure. The overall aesthetic is futuristic and technological, suggesting a neural network or data connectivity.

**TRAINING ON DGX-1**

The background features a complex network of thin, glowing green lines connecting various nodes. Some nodes are bright green, while others are a soft, out-of-focus blue. The overall effect is a sense of digital connectivity and data flow against a dark, almost black background.

# DEPLOYING ON JETSON AGX XAVIER

# JETSON AGX XAVIER DEVELOPER KIT

<https://developer.nvidia.com/embedded/jetson-agx-xavier-developer-kit>



- Install the latest JetPack (currently 4.2.2)
- Follow the instructions in the TLT Getting Started Guide
  - Download tlt-converter from the NVIDIA dev zone.
  - Install Open SSL:  
`sudo apt-get install libssl-dev`
- Copy your `.etlt` and `.bin` files to your Jetson device.

# INFERENCE PERFORMANCE

My model: **DetectNet v2** with **ResNet 50** backbone; 768 x 768 pixel video frames.

Number of streams	Precision	Total FPS
1	FP32	11
1	FP16	40
1	INT8	60
4 (interval + tracker)	INT8	240 (60/stream)
8 (interval + tracker)	INT8	251 (31/stream)



# START USING TRANSFER LEARNING TOOLKIT

<https://developer.nvidia.com/transfer-learning-toolkit>

- Sign up for a free NVIDIA GPU Cloud (NGC) account
- Download the TLT for IVA Docker container
  - `docker pull nvcr.io/nvidia/tlt-streamanalytics:v1.0_py2`
- Train, prune, re-train, export & deploy!
- Let me know which problems you have quickly and accurately solved with the NVIDIA IVA tools!
  - [jskinner@nvidia.com](mailto:jskinner@nvidia.com)

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November 4 - 6, 2019 | Washington, D.C.



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